Tutorial 11

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FFT

A polynomial of power n-1:

$$p(x) = \sum_{i=0}^{n-1} a_i x^i$$

$$= \left\langle \begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix}, \begin{bmatrix} x^0 \\ \vdots \\ x^{n-1} \end{bmatrix} \right\rangle$$

which is called the coefficient representation of the polynomial. Value representation: We will say that $\{(x_i, y_i)\}_{i=0}^{n-1}$ is the value representation of the polynomial $\forall i = 0 \dots n-1: \ p\left(x_i\right) = 0$ y_i .

Theorem 1 (Lagrangian algorithm). For every set of n points $\{(x_i, y_i)\}_{i=0}^{n-1}$ where all the xs are different, then there exists a single polynomial of power $\leq n-1$ such that $p(x_i) = y_i$ for every i.

Proof. (Not exactly a proof, not written as such elsewhere)

Let there be the value representing vector

$$v = (p(x_0), \dots, p(x_{n-1}))$$

So

$$v = V \begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix}$$

Where V is the Vandermonde matrix, which is invertible if and only if $\forall i \neq j, \ x_i \neq x_j$. Since the Vandermonde matrix is of size $n \times n$, the naive method to change representation is $O(n^2)$, but perhaps we can do this in $O(n \log(n))$? Multiplying polynomials: Let there be p(x), q(x), we are given x_0, \ldots, x_{n-1} at the beginning.

$$p(x_0) q(x_0) = p \cdot q(x_0) \implies O(n)$$

$$\begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix} \cdot \begin{bmatrix} b_0 \\ \vdots \\ b_{n-1} \end{bmatrix} = O(n^2)$$

so, we would much rather calculate multiplication from the coefficient representation than the value representation, but transferring between the representations through multiplying by Vandermonde takes $O(n^2)$.

$\mathbf{2}$ Convolution

Definition 2.1 (Convolution (linear)). Given $a = (a_0, ..., a_{n-1})$, $b = (b_0, ..., b_{m-1})$, then let $c = a * b = (c_0, ..., c_{n+m-2})$, where

$$c_i = \sum_{j=0}^i a_j b_{i-j}$$

and if an index does not exist, it is defined to be 0.

Example 1.

$$a = (a_0, a_1, a_2)$$

$$b = (b_0, b_1)$$

$$c_0 = a_0 b_0$$

$$c_1 = a_0 b_1 + b_0 a_1$$

$$c_2 = a_1 b_1 + b_0 a_2 + (b_2 a_0 = 0)$$

$$c_3 = b_1 a_2 + (a_1 b_2 = 0)$$

Consider:

$$(b_0x^0 + b_1x^1)(a_0x^0 + a_1x^1 + a_2x^2) = b_0a_0x^0 + (a_0b_1 + a_1b_0)x^1 + (b_1a_1 + b_0a_2)x^2 + (b_1a_2)x^3$$
$$= c_0x^0 + c_1x^1 + c_2x^2 + c_3x^3$$

So we can see that multiplying polynomials is simply an instance of convolution!

2.1 Uses of convolution

2.1.1 Pattern matching

Input: 2 strings $s \in \{\pm 1\}^n$, $p \in \{\pm 1\}^m$, we will assume without loss of generality $m \le n$ **Output:** Every index in s where they start a continuous series of p

Example:

$$s = (1, -1, 1, 1, -1, 1)$$

$$p = (1, -1, 1)$$

$$D = \{0, 3\}$$

Naive solution: We may solve this by passing over all of s, and checking if p appears: O(nm)

We will see a more efficient solution with FFT/convolution:

$$s_0p_0 + s_1p_1 + s_2p_2 = m$$

So we know that there is an instance of p at index 0.

$$s_3p_0 + s_4p_1 + s_5p_2 = m$$

This also holds true, but how do we get here from convolution? Let us consider

$$\begin{split} s &= (1, -1, 1) \\ p &= (a, b, c) \\ (s * p)_0 &= 1 \cdot a \\ (s * p)_1 &= 1 \cdot b + (-1) \cdot a \\ (s * p)_2 &= 1 \cdot a + 1 \cdot c + (-1) \cdot b \end{split}$$

Notice that at $(s*p)_2$ that is the same as performing s_0p_0,\ldots on the **inverse** of p.

Efficient algorithm:

- 1. We will find p^R where $\forall i = 0, \dots, m-1$ $p_i^R = p_{m-1-i}$: O(m)
- 2. We will find the convolution of p^R with s, and call it c: We will use a fast algorithm for multiplying polynomials based off FFT in $O(n \log(n))$
- 3. We will define and return

$$D = \{k : c_{k+m-1} = m\}$$

$$O(n+m)$$

Runtime: $O(m) + O(n \log(n)) + O(n + m) = O(n \log n)$ Correctness:

Theorem 2. $C_{k+m-1} = m \Leftrightarrow there \ exists \ a \ continuous \ p \ at \ s_k \Leftrightarrow s_k s_{k+1} \dots s_{k+m-1} = p \Leftrightarrow \forall i = 0 \dots m-1 \ s_{k+i} = p_i$ Proof.

$$c_{i} \stackrel{def}{=} \sum_{j=0}^{i} s_{j} p_{i-j}^{R}$$

$$\implies c_{k+m-1} \stackrel{def}{=} \sum_{j=0}^{k+m-1} s_{j} p_{k+m-1-j}^{R}$$

$$\text{Definition of } p^{R} = \sum_{j=0}^{k+m-1} s_{j} p_{j-k}$$

$$= \sum_{j=0}^{k} s_{j} p_{j-k} + \sum_{j=k}^{k+m-1} s_{j} p_{j-k}$$

$$(j \le k-1 \implies j-k < 0 \implies p_{j-k} = 0) = 0 + \sum_{j=k}^{k+m-1} s_{j} p_{j-k}$$

$$(i = j-k \ j = i+k) = \sum_{i=0}^{m-1} s_{i+k} p_{i}$$

$$\implies c_{k+m-1} = \sum_{i=0}^{m-1} s_{i+k} p_{i}$$

So our theorem is now

$$\sum_{i=0}^{m-1} s + k + ip_i = m \Leftrightarrow \dots$$

 $s_{ki}p_i \in \{1, -1, 0\}$, from the definition of s, p convolution. The sum over m variables therefore

$$\sum_{i=0}^{m-1} s_{k+i} p_i \le m$$

with equality when all the variables are 1, which happens from the definitions of s, p when for all i = 0, ..., m-1 $s_{k+i} = p_i \neq 0$, which is the definition of the continuous appearance of p at the start s_k .

3 DFT - Discrete Fourier Transform

Given a polynomial with the coefficient vector $\begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix}$, then

$$DFT_n \left(\begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix} \right) = \begin{bmatrix} p \left(\omega_n^0 \right) \\ \vdots \\ p \left(\omega_n^{n-1} \right) \end{bmatrix}$$

which is a representation of the nth roots of unity.

$$DFT_n\left(\begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix}\right) = F\begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix} = \begin{bmatrix} \left(\omega_n^0\right)^0 & \dots & \left(\omega_n^0\right)^{n-1} \\ \vdots & \ddots & \vdots \\ \left(\omega_n^{n-1}\right)^0 & \dots & \left(\omega_n^{n-1}\right)^{n-1} \end{bmatrix} \begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix}$$

where

$$F_{ij} = \left(\omega_n^i\right)^j$$

4 FFT - Fast Fourier Transform

This is the algorithm for finding DFT in $O(n \log (n))$.

4.1 Polynomial multiplication

Input: $p = (a_0, ..., a_{n-1}), q = (b_0, ..., b_{n-1})$ Output: $qp = (c_0, ..., c_{2n-2})$ Algorithm:

- 1. We will bolster with 0s q, p to the smallest power of 2 which is greater than or equal to 2n 1, and call them $\overline{p}, \overline{q} \in \mathbb{C}^{2^k} : 2n 1 \leq 2^k$
- 2. We will calculate $FFT(\overline{p})$, $FFT(\overline{q})$, and we have got the value representations
- 3. We will multiply value value, and get the value representation of \overline{pq}
- 4. We will return the coefficient representation with FFT^{-1} :

$$q \cdot p = FFT^{-1} \left(FFT \left(\overline{p} \right) \cdot FFT \left(\overline{q} \right) \right)$$

Runtime:

- 1. Bolstering: O(n)
- 2. FFT: $O(n \log(n))$
- 3. Value value multiplication: O(n)
- 4. Inverse FFT: $O(n \log(n))$

Total: $O(n \log(n))$